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climbing robots were also researched, such as an inchworm design and RC helicopters. After comparing various design ideas the group determined that a six legged modular design would best suit the requirements of the project.

DESIGN AND CONSTRUCTION OF A TREE CLIMBING ROBOT

This research work focuses on wireless controlled robotic arm using DTMF (Dual tone multi frequency) technique. The arm is designed to be a part of a coconut tree climbing robot.

(PDF) Robotic Arm Design for Coconut-Tree Climbing Robot

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Hariskrishna TV et al International Journal of Current Engineering and Technology, Special Issue-3, (April 2014)

Design of Climbing Mechanism for a Tree Climbing Robot

ii Abstract This report describes the research, mechanical analysis, design methodology, and testing procedures that were used to design and build a tree-climbing robot.

Design and Construction of a Tree-Climbing Robot

Climbing robot is a challenging research topic that has gained much attention from researchers. Most of the robots reported in the literature are designed to climb on manmade structures, but seldom robots are designed for climbing natural environment such as trees.

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design and implementation of an autonomous climbing robot a dissertation submitted to the department of computer science and the committee on graduate studies

DESIGN AND IMPLEMENTATION OF AN AUTONOMOUS A DISSERTATION

Climbing robot is a challenging research topic that has gained much attention from researchers. Most of the robots reported in the literature are designed to climb on manmade structures, but seldom robots are designed for climbing natural environment such as trees.

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structure and function that could inspire the design of a legged climbing robot. Autumn et al. [21] have measured the Autumn et al. [21] have measured the dynamics of gecko climbing and here we report preliminary results on cockroaches [22].

The RiSE Climbing Robot: Body and Leg Design

modifications to the robot design Journal of Automation and Control Engineering Vol. 4, No. 3, June 2016

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